

FORM PTO-1449  
(Rev. 7-80)U.S. DEPARTMENT OF COMMERCE  
PATENT AND TRADEMARK OFFICEAtty. Docket No.  
14395Serial No.  
10/615,595**LIST OF PRIOR ART CITED BY APPLICANT**  
(Use several sheets if necessary)APPLICANT  
KHAJEPOUR et al.FILING DATE  
July 9, 2003GROUP  
3652

## U.S. PATENT DOCUMENTS

EXAMINE R INITIAL		DOCUMENT NUMBER							DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
/DU/	AA	3	2	8	6	8	5	1	11-22-1966	Sperg			
/DU/	AB	3	4	9	7	0	8	3	02-24-1970	Anderson			
/DU/	AC	3	6	3	1	7	3	7	01-04-1970 <sup>2</sup>	Wells			
	AD	<del>4</del>	<del>6</del>	<del>6</del>	<del>6</del>	<del>3</del>	<del>6</del>	<del>2</del>	<del>05-19-1987</del>	<del>Landsberger et al.</del>			
/DU/	AE	4	6	8	3	7	7	3	08-04-1987	Diamond			
	AF	<del>4</del>	<del>9</del>	<del>7</del>	<del>6</del>	<del>5</del>	<del>8</del>	<del>2</del>	<del>12-11-1990</del>	<del>Clavel</del>			
	AG	<del>5</del>	<del>3</del>	<del>1</del>	<del>3</del>	<del>8</del>	<del>5</del>	<del>4</del>	<del>05-25-1994</del>	<del>Akeel</del>			
/DU/	AH	5	3	3	3	5	1	4	08-02-1994	Toyama et al.			
/DU/	AI	5	9	6	7	7	2	9	10-19-1999	Foes			

## OTHER PRIOR ART (Including Author, Title, Date, Pertinent Pages, Etc.)

/DU/	BA		"Delta, a Fast Robot with Parallel Geometry", R. Clavel, Proc. Int. Symposium on Industrial robots, April 1988, pp. 91-100.										
/DU/	BB		"Kinematics of a Three-DOF Platform with Three Extensible Limbs", Lung-Wen Tsai, Recent Advances in Robot Kinematics, pp. 401-409.										
/DU/	BC		"A Smart Kinestatic Interactive Platform", M. Griffis et al., Advances in Robot Kinematics and Computationed Geometry, pp. 459-464.										
/DU/	BD		"Development of an Ultrahigh speed Robot FALCON using Wire Drive System", S. Kawamura et al., IEEE International Conference on Robotics and Automation 1995, pp. 215-220.										

EXAMINER /Donald Underwood/

DATE CONSIDERED 12/09/2007

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 602; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.